

### EEL 5245 POWER ELECTRONICS I Lecture #3: Chapter 2 Switching Concepts



#### **Discussion Topics**

- Homework Assignment #1
- Need for Switching in Power Electronic Converters
  - Example on Efficiency Comparison
- Ideal Switch Characteristics
- Comparison to Practical Switch
- Power Loss in Practical Switch
- Several Examples on Switch Loss Calculation (Conduction and Switching components of Loss)-(Batarseh)



#### **Homework Assignment #1**

Exercises:

E2.1, E2.3

Problems:

P2.2, P2.3, P2.4, P2.6

Due Wednesday, September 3, 2014 Submit via email



#### **Homework Corrections-Hw #1**

- Direct Homework questions to:
- Answers per solution manual and need to be verified
- Problem 2.2- R is  $5\Omega$ 
  - (a.) Ans. -80V
  - (b.) Ans. 1600W
  - (c.) Ans. 100%
- Problem 2.3
  - Vo,avg=2\*Delta\*Idc\*R
- Problem 2.4-
  - Like class example (easier), Find Psw(t), Pavg=.302W



#### **Homework Corrections-Hw #2**

- Answers per solution manual and need to be verified
- **Problem 2.8- Von=.7V** 
  - (a.) Ans. Psw=32.5W
  - (b.) Ans. Pcond=9.59W
- Problem 2.10
  - **Do** (a.)-(c.) only, skip (d)
  - (b.) Ans. Po,avg=.5\*fs\*Voff\*Ion\*(2\*td+tf+tr)
  - (c.) Ans. Po,avg=54W

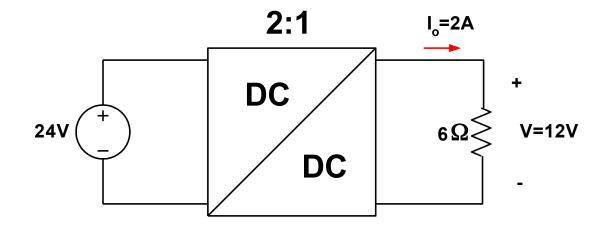


#### **Need for Switching**

- Why use semiconductor devices as switches?
  - Allows better output control
  - Allows for improved efficiency
    - Ideally 100%
- What are effects of poor efficiency?
  - Energy costs
  - Design complications
  - Reduce reliability-(More losses mean more heat)
  - More component design
    - Heat transfer
    - Protection



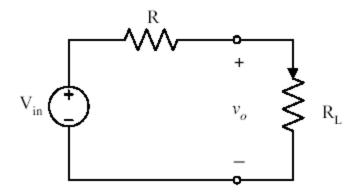
#### Theoretical Efficiency Example



- We'll do an example to underscore why switching is the most energy efficient choice
- Consider the design of a DC-DC converter as shown above
- Design requires 24V step down to 12V across a 6 Ohm resistive load
- Let's investigate, some possible options



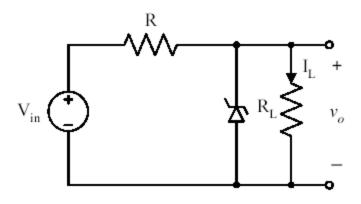
# Theoretical Efficiency Example Voltage Divider



- A simple voltage divider can do job
- R must be set to 6  $\Omega$
- Load cannot change-R fixed so no opportunity for control
- Losses are high η=50%



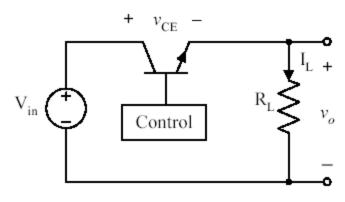
# Theoretical Efficiency Example Zener Regulator

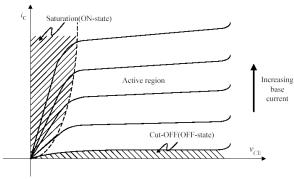


- Need some control (regulation)
- A Zener Regulator will allow for load variation
- Assume Vz=12V, Iz@12V=.2A,  $Rdrop=5.5\Omega$
- Pin=Pout+Prdrop+Pzener=24W+26.2W+2.4W=52.6W
- $\eta=46\%$



### Theoretical Efficiency Example Linear Regulator

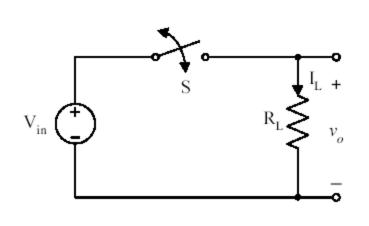


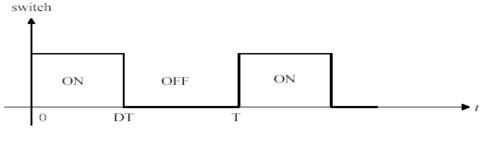


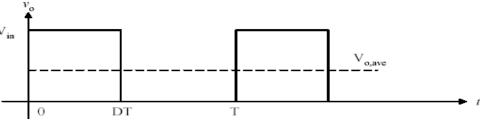
- Drop resistor inefficient means
- Direct source connection is preferable
- Try linear regulator (Similar to implementation 7805, LM317 etc.
- Assume Vce=12V
- Pin=Pout+Pnpnloss=24W+24W=50W
- η=50%



### Theoretical Efficiency Example Duty Ratio Controlled Switch







$$V_{o,ave} = \frac{1}{T} \int_{0}^{TD} V_{in} dt = V_{in}D$$

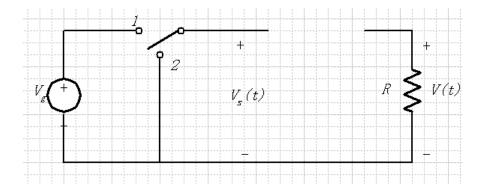
- Instead of operating transistor in active mode try using as switch
- Low Pass filter required to extract DC
- η=100%



# Circuit Implementation Duty Ratio Controlled Switch-SPDT

SPDT switch changes do component

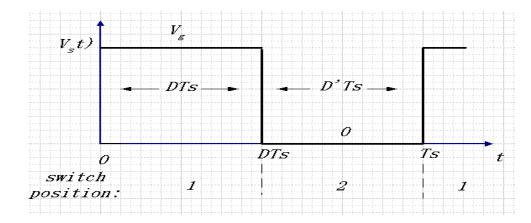
 Note-all power semiconductor devices act as SPST switch



Switch output voltage waveform

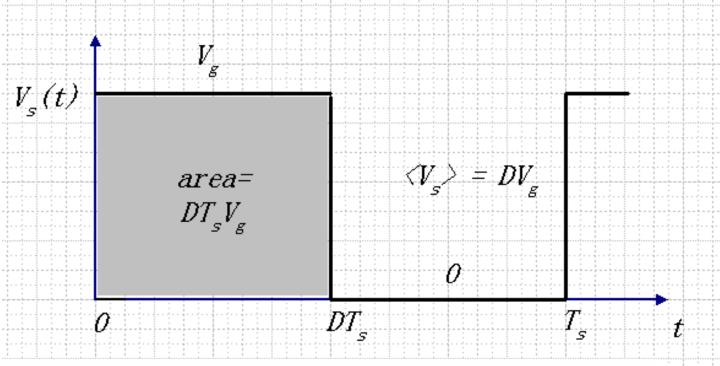
Duty cycle D:  $0 \le D \le 1$ 

complement D': D' = 1 - D





#### **DC** Component



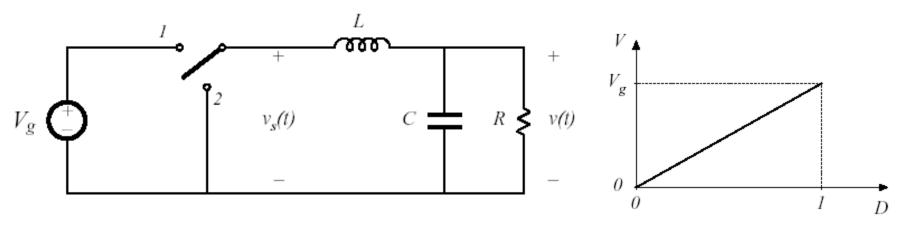
Fourier analysis: Dc component = average value

$$\langle v_s \rangle = \frac{1}{T_s} \int_0^{T_s} v_s(t) dt$$
  
 $\langle v_s \rangle = \frac{1}{T_s} (DT_s V_g) = DV_g$ 

$$\langle v_s \rangle = \frac{1}{T_s} (DT_s V_g) = DV_g$$



#### **Step Down Converter-Buck**



- Low Pass extracts DC
- Position 2 allows for current "freewheeling"
- Vo can be controlled by adjusting D (Switching Period/ Frequency Fixed), Vo/Vin = D
- Ideally, is no switch/filter loss,  $\eta=100\%$ 
  - We assume an ideal switch here



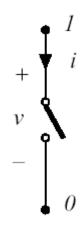
#### **Summary of Example**

- Step down converter (Buck) exemplifies how waveform "chopping" allows control output
- Waveform modification by "chopping" is fundamental premise in Power Electronics
- If switch ideal, no losses
- By controlling D, Vo is controlled, independent of load
- Clearly, for an ideal switch, this example is the best approach
- In reality, switch not ideal (switching/conduction losses)
- "Chopping" means harmonics at both input/output (EMI)
- Is the assumption of an ideal switch reasonable?



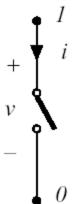
#### **Ideal Switch Characteristics**

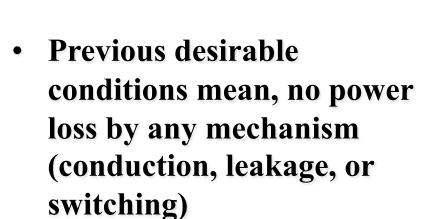
- Zero on-state resistance
  - No forward voltage drop when on
- Infinite off-state resistance
  - No leakage current when off
- Current limitless when on-either direction
  - Conduction current a function of external components only
- No limit on amount of voltage across switch when off
  - Blocking voltage infinite (forward or reverse)
- Switch can transition from on-off or off-on instantaneously when commanded to



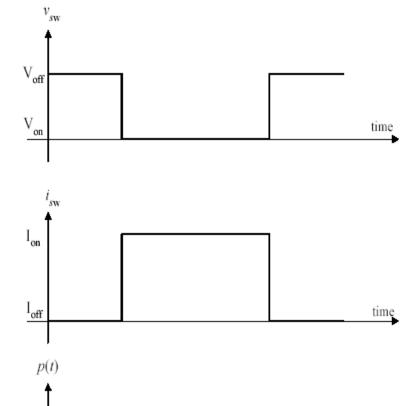


## Ideal Switch i-v Characteristics (Transition)





- Switch transition-No overlap
- Von=0V, Ioff=0A



time



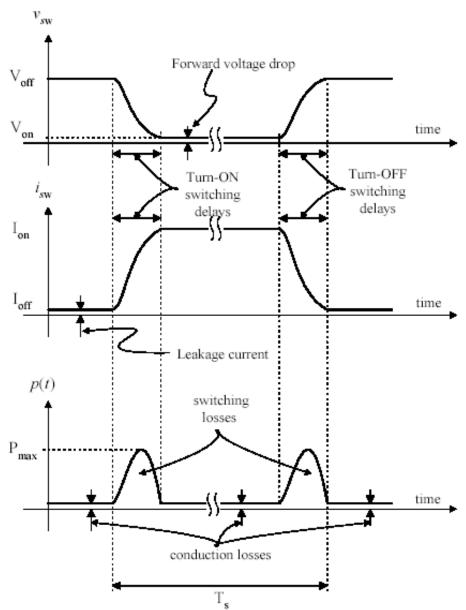
#### **Practical Switch**

- Although Semiconductor Industry has produced amazing devices, the "real world" switch is not ideal
  - Limited conduction current when the switch on, limited blocking voltage when the switch is in the off
    - Both are directional in practical switch
  - Limited switching speed that caused by the finite turnon and turn-off times
    - Real world (Semiconductor) switches are charge driven
  - Finite, nonzero on-state and off-state resistances
    - There is a I^2R loss when on and some leakage when off (very small)

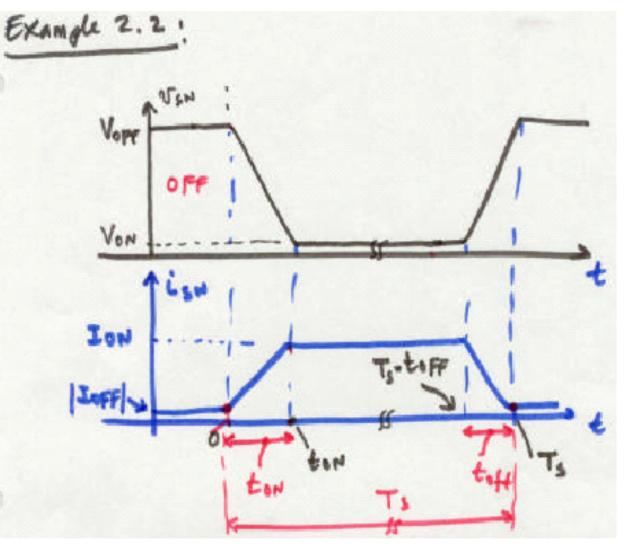


# Practical Switch i-v Characteristics (Transition)

- This is root cause of the single major source of loss in PE converters
  - Conduction- When switch is in on state (off state too, to a lesser degree)
  - Switching Losses When switch is transitioning from on to off or off to on







- Derive expression for instantaneous power,  $p(t)=v_{sw}*i_{sw}$
- Determine average power dissipation over one switching cycle, Ts



$$i_{SM} = \begin{cases} \frac{t}{t_{oN}} & (I_{oN} - I_{opp}) + I_{opp} & 0 \leqslant t \leqslant t_{on} \\ I_{oM} & t_{oN} \leqslant t \leqslant t_{s} - t_{opp} \\ -\frac{t-T_{s}}{t_{opp}} & (I_{oN} - I_{opp}) + I_{opp} \\ T_{s} - t_{opp} & \leqslant t \leqslant T_{s} \end{cases}$$

$$T_{s} - t_{opp} & (t - t_{on}) + V_{on} \\ V_{on} & V_{opp} - V_{on} & (t - t_{s} + t_{opp}) + V_{on} \\ \frac{V_{opp} - V_{on}}{t_{opp}} & (t - (T_{s} + t_{opp})) + V_{on} \end{cases}$$



The instantaneous power, 
$$P(t)$$
, is given by

$$P(t) = U_{SW} U_{SW}$$

Assum  $Ioff \approx 0$  &  $V_{OM} \approx 0$ 

$$-\frac{V_{OFF} I_{ON}}{t_{ON}} (t - t_{ON})t \quad 0 < t < t_{ON}$$

$$P(t) = V_{ON} I_{ON} P_{2} \quad t_{ON} \leq t < T_{S} - t_{OFF}$$

$$-\frac{V_{OFF} I_{ON}}{P_{3}} \quad T_{S} - t_{OFF} \leq t < T_{S}$$

$$P_{3} t_{OFF} I_{OFF} \quad T_{S} - t_{OFF})(t - T_{S})$$



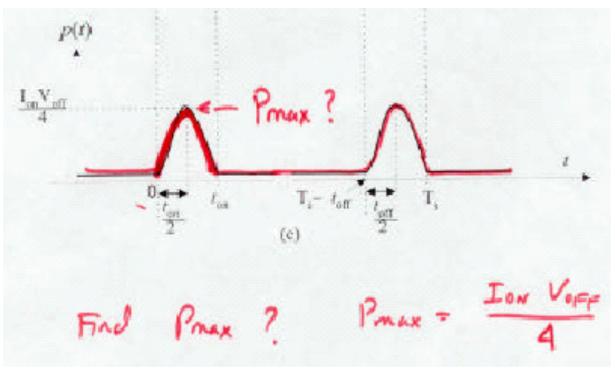
c) 
$$P_{ave} = \frac{1}{T_s} \int_{0}^{T_s} P(t) dt$$

$$= \frac{1}{T_s} \left[ \int_{0}^{T_s} P_1(t) dt + \int_{0}^{T_s} P_2 dt + \int_{0}^{T_s} P_3 dt \right]$$

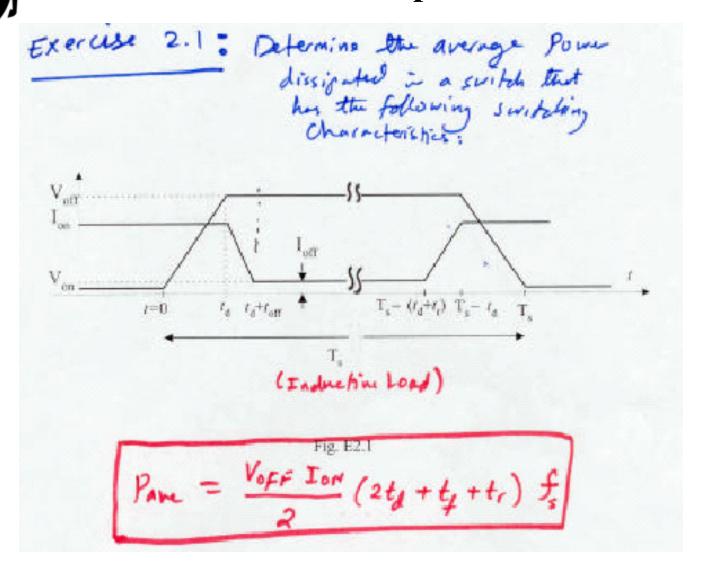
$$= \frac{V_{OFF} I_{ON}}{6T_s} \left( t_{IN} + t_{OFF} \right) + \frac{V_{ON} I_{ON}}{T_s} \left( T_s - (t_{eN} + t_{OFF}) \right)$$





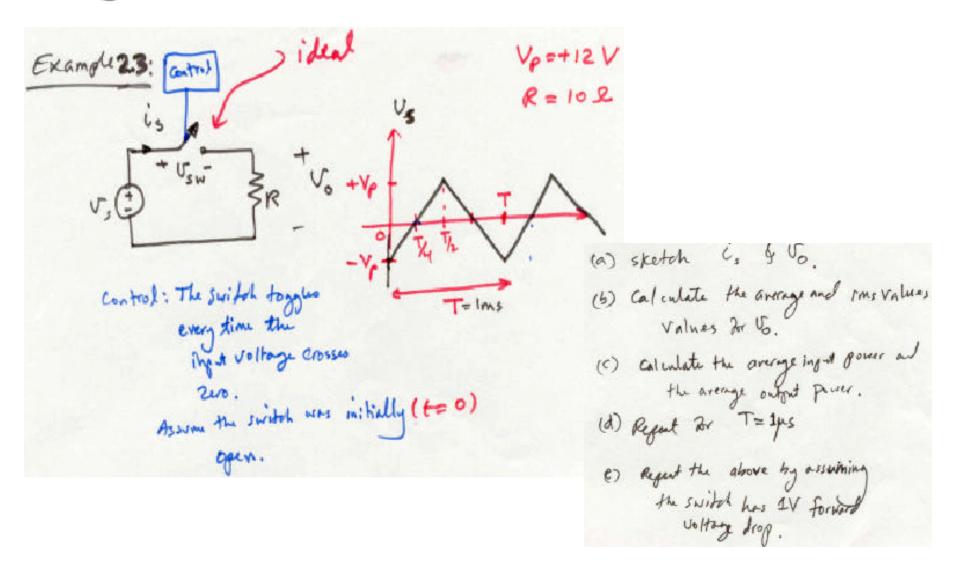


### **Spother Switch Loss Example**



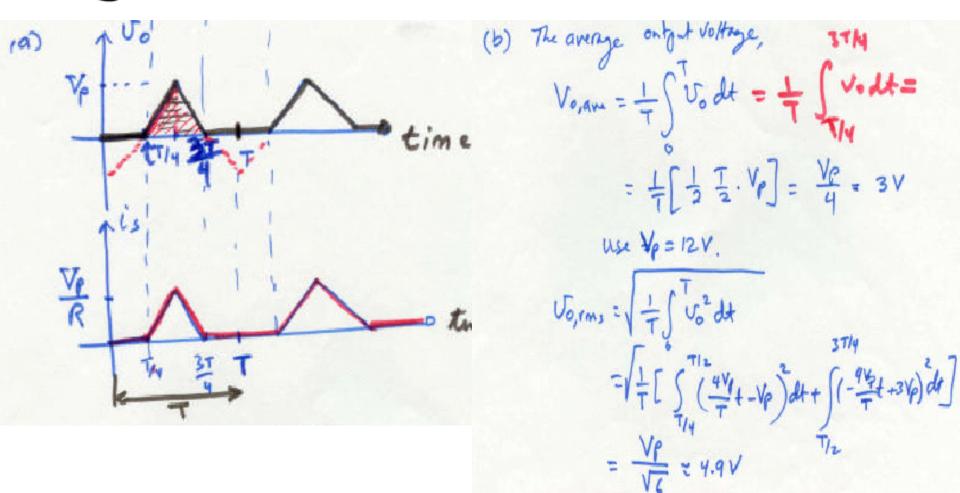


### **Leample on Vo Control**





## Lample on Vo Control





### 🛂 Example on Vo Control

Figure 1 Signal = 
$$\frac{1}{TR} \int_{0.5}^{T} U_{s}^{2} dt$$

$$= \frac{V_{e}^{2}}{6R} = \frac{I2^{2}}{6 \times 10 R} = 2.4 W$$

Fout =  $\frac{1}{T} \int_{0.5}^{T} U_{s}^{2} dt + \frac{1}{T} \int_{0.5}^{T} U_{s}^{2} dt$ 

$$= \frac{1}{T} \left[ \frac{1}{T} \int_{0.5}^{T} U_{s}^{2} dt + \frac{1}{T} \int_{0.5}^{T} U_{s}^{2} dt \right]$$

$$= \frac{V_{e}^{2}}{6R} = 2.4 W$$



## **Example on Vo Control**

$$V_{0,rms} = \sqrt{\frac{1}{6V_{P}}[(V_{P}-1)^{3}+1]}$$

$$= 4.3V$$

$$P_{in,ave} = \frac{1}{4R}(\frac{2V_{I}^{2}}{3}-1)$$

$$= 2.375 W$$

$$P_{0,ave} = \frac{1}{R6V_{P}}[(V_{I}-1)^{3}+1] = 1.85 W$$

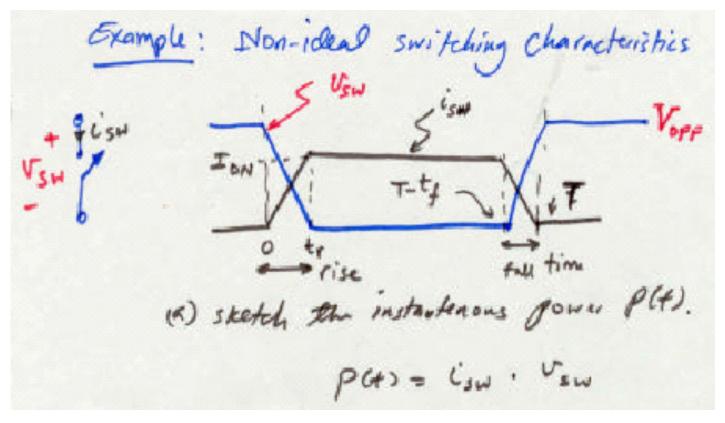
$$V_{0,AWL} = \frac{1}{T} \int_{0}^{T} \frac{dt}{dt}$$

$$= \frac{1}{T} \left[ \int_{0}^{T} \frac{dV_{0}}{dt} + V_{0} - 1 \right] dt$$

$$+ \int_{0}^{T} \left( \frac{-dV_{0}}{T} dt + 3V_{0} - 1 \right) dt$$

$$= \frac{V_{0}}{dt} - \frac{1}{2} = 2.5V$$







i) For 
$$0 < t < t_V$$

$$isu(t) = \frac{Io_N}{t_r}(t-0)$$

$$V_{SM}(t) = \frac{V_{OF,F}}{t_r}(t-t_r)$$

$$= -\frac{Io_N}{t_r^2}(t-t_r) t$$

$$ii) For  $t_V < t_V < t_V < t_V < t_S - t_S$ 

$$V_{SM} = O$$

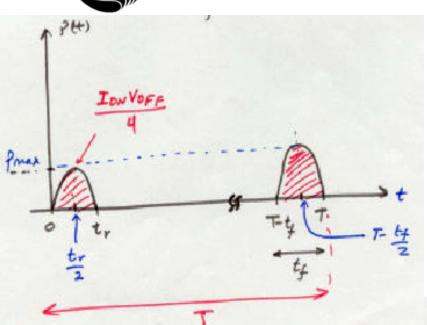
$$V_{SM} = O$$$$

(iii) For T-ty (t { T  

$$i_{sw}(t) = \frac{I_{sw}}{t_f}(t-T)$$

$$V_{sw}(t) = \frac{V_{oper}}{t_f}(t-(T-t_f))$$

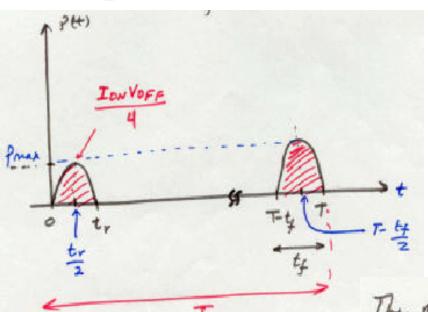




$$P(t) = \begin{cases} -\frac{I_{ON} V_{OFF}}{t_i^2} (t - t_i)t & o < t < t_f \\ 0 & t_i < t < T - t_g \\ -\frac{I_{ON} V_{OFF}}{t_i^2} (t - (t - T))(t - T) T - t_g < t < T \end{cases}$$

$$T_{ON} V_{OFF}$$





$$\frac{dP_c(t)}{dt}\Big| = 0 = \frac{-T_{ON}V_{OI}=F}{t_r^2}(2t-t_r)\Big| = 0$$

$$t=t_{min}$$



Should be tr+tf